# TRANSITION \& Motor control 

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## OBJECTIVES

- Different combinations of TMs
- Load curve(s) of Main

Gen/Alternator
Limitations of speeds
Transition $\&$ its type
> Different Transitions
Transition Components -for checking during trouble shootings MAIN GEN./ALTERNATOR WITH FULL FIELD


## TR. MOTORS COBINATIONS ACROSS THE MAIN GEN./ALTERNATOR WITH WEAK FIELD



## LOAD CURVE OF mAIN GEN./ALTERNATOR SET BY EXCITA

## SYCTFM

If speed of TMs increases
$\rightarrow$ Back EMF increases
$\rightarrow$ Equivalent Resistance increases
$\rightarrow$ The operating pt.moves from 'B' to 'C'

If speed of TMs decreases
$\rightarrow$ Back EMF decreases
$\rightarrow$ Equivalent Resistance decreases
$\rightarrow$ The operating pt.moves from 'C' to 'B'


## LOAD CURVE AT EACH NOTCH (FROM $1^{\text {TH }}$ TO $8^{\text {TH }}$ NOTCH)SET BY

 EXCITATION SYSTEM

## LIMITATIONS OF TMS SPEEDS

If the speed of TMs increases

- The voltage increases and reaches its limit (C)
- The corresponding speed is also limited
If the speed of TMs decrea The current increases ar reaches its limit(B)

- The corresponding speed is also limited


## TRANSITION

- Implies change(s) of
i)TMs combinations
(SP to P or P to SP )
ii) TMs field excitation

> (FF to WF or WF to FF)
iii)Both of above
-Done for speed increase
or decrease when it reaches
the limit of maximum
Gen. voltage(C) or Current(B).


## AUTOMATIC TRANSITION

- Transition is done automatically by control circuits
- The control circuit operates at corresponding speeds when the $M / G e n$ voltage or current reaches the limits ( C or B ) of the constant load curi M/Gen.


## TRANSITION-TYPE

## FORWARD TRANSITION

-Done for speed increase

## BACKWARD TRANSITION

-Done for speed decrease

## FORWARD TRANSITION

## Done when -

Gen. Voltage reaches at its Maximum limit(C)

## Done by -

Reducing the back emf of TMs' combination thereby reducing of the Main Gen. Voltage

## BACKWARD TRANSITION

## Done when -

тhe Gen. current reaches at its Maximum limit(B)

## Done by -

 Increasing the back emf of TMs' combination thereby increasing …...! of the Main Gen. Voltage
## Sequence of different Transition

| Sequence of Transitions | Events <br> (Changes in TMs circuitry) |
| :--- | :--- |
| FORWARD | TRANSITIONS |
| $1^{\text {st }}$ Transition | SPFF $\rightarrow$ SPWF |
| $2^{\text {nd }}$ Transition | SPWF $\rightarrow$ PFF |
| $3^{\text {rd }}$ Transition | PFF $\rightarrow$ PWF |
| BACKWARD | TRANSITIONS |
| $1^{\text {st }}$ Transition | PWF $\rightarrow$ PFF |
| $2^{\text {nd }}$ Transition | PFF $\rightarrow$ SPWF |
| $3^{\text {rd }}$ Transition | SPWF $\rightarrow$ SPFF |

## INITIAL ARRANGEMENT OF CIRCUITARY OF TMS <br> : PWF $\rightarrow$ PWF

- At stand still the TMS draw very high current(I)
- As TI al ${ }_{A} I_{F}$ i.e. $T a I^{2}$; a good initial torque (T) develops which causes rotation of TMs
- The rotation creates Back EMF ( $\mathrm{E}_{\mathrm{F}}$ a N. $\Phi$ ) from the TMS.
- M/Gen. Voltage (V)also rises and reaches at ' $B$ '.



## $1^{\text {st }}$ TRANSITION :

## SPFF $\rightarrow$ SPWF

- As the speeds of TMs increase the Back EMFs of TMs will also increase
- The M/Gen. Voltage rises (Current reduces)when the operating pt. traverse from ' $B$ ' to ' $C$ '
- The operating pt. will not go beyond ' $C$ ' because the voltage
 limitation already established by automatic excitation control system can not be exceeded.
- The speed of the loco will be stable at 29 KMPH corresponding to pt.'C'
- To increase speeds back emfs of TMs are decreased by SPFF to SPWF circuitry conversion such that
' $P$ ' is brought at B ' . (1st Transition)



## $2^{\text {ND }}$ TRANSITION :SPWF $\rightarrow$ PFF

- As the speeds of TMs increase further the Back EMFs of TMs will also increase
- The M/Gen. Voltage rises (Current reduces)when the operating traverse from ' $B$ ' to ' $C$ '
- The speed of the loco will be stable at 47 KMPH corresponding t pt.'C'
- To increase speeds back emfs of TMs are decri PFF circuitry conversion such that



## $3^{\text {rd }}$ <br> TRANSITION

 PFF $\rightarrow$ PWF- As the speeds of TMs increase further the Back EMFs of TMs will also increase

- The M/Gen. Voltage rises (Current reduces)when the operating pt. traverse from ' $B$ ' to ' $C$ '
- The speed of the loco will be stable at 81 KMPH corresponding to pt.' C '
- To increase speeds back emfs of TMs are decreased by PFF to PWF circuitry conversion such that ' $P$ ' is brought at ' $B$ '. ( $3^{\text {nd }}$ Transition)




## COMPONENTS OF TRANSITION

## -Axle Generator

## - Transition Excitation Transformer

Transition Regulating Panel

## AXLE GENERATOR (ALTERNATOR)

- 40 poles imbedded in the plastic stator
- Rotor - shaft driven by Axle no. 2
- L-shaped \& straight soft iron bars in the rotor as flux guide to stator coil
- Output voltage induced in stator coil with the frequency proportional speed.



## TRANSITION EXCITATION TRANSFORMER (TET)

- A saturable Transformer
- Located on the front panel
- Output is volt-time pulse
Speed proportional to no.
of to pulse
More speed, More pulses and more average voltage


## TRANSITION REGULATING

 PANEL (TRP)- Located on the front panel
- Comprises a set of electronic circuit cards
- Card No.210-

Transition Cards
Card no.-207 Miscellaneous Card No. of card no. $210=$

No. of Transitions( 1,2
or 3)



POWER CIRCUIT

## CIRCUIT OPERATION




PROPUSION CONTROL

## TROUBLE SHOOTING:

- Transition is not picking up-----
1.Axle Gen. Cable open.

2. Wiring of Transition Transformer open or not perfect.

- $1^{\text {st }}$ Transition is not picking up----
1.Card no. 210-1 is loose
2.FSR coil is not perfect
- $2^{\text {nd }}$ Transition is not picking up----
1.Card no. 210-2 is loose
2.TR coil is not perfect/ Emergency TR can be used manually. $3^{\text {rd }}$ Transition is not picking up----
1.Card no. 210-3 is loose


